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(13A02302) ELECTRICAL CIRCUITS AND SIMULATION LAB

PART-A: ELECTRICAL CIRCUITS

- 1) Verification of Thevenin's and Norton's Theorems
- 2) Verification of Superposition Theorem and Maximum Power Transfer Theorem
- 3) Verification of Compensation Theorem
- 4) Verification of Reciprocity, Millmann's Theorems
- 5) Locus Diagrams of RL and RC Series Circuits
- 6) Series and Parallel Resonance
- 7) Determination of Self, Mutual Inductances and Coefficient of Coupling
- 8) Z and Y Parameters
- 9) Transmission and Hybrid Parameters
- 10) Measurement of Active Power for Star and Delta Connected Balanced Loads
- 11) Measurement of Reactive Power for Star and Delta Connected Balanced Loads
- 12) Measurement of 3-Phase Power by Two Wattmeter Method for Unbalanced Loads

PART-B: PSPICE SIMULATION

- 1) Simulation of DC Circuits
- 2) DC Transient Response
- 3) Mesh Analysis
- 4) Nodal Analysis

NOTE:

- PSPICE Software Package is Necessary.
- Eight Experiments are to be Conducted from PART-A and any two from PART-B

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(13A02401) ELECTROMAGNETIC FIELDS

Course Objective:

• The objective of this course is to introduce the concepts of electric field and magnetic fields and their applications which will be utilized in the development of the theory for power transmission lines and electrical machines.

UNIT I

ELECTROSTATICS

Electrostatic Fields - Coulomb's Law - Electric Field Intensity(EFI) due to Line, Surface and Volume charges- Work Done in Moving a Point Charge in Electrostatic Field-Electric Potential due to point charges, line charges and Volume Charges - Properties of Potential Functions-Potential Gradient - Gauss's Law-Application of Gauss's Law-Maxwell's First Law, Laplace's Equation and Poisson's Equations - Solution of Laplace's Equation in one Variable.

Electric Dipole - Dipole Moment - Potential and EFI due to Electric Dipole - Torque on an Electric Dipole in an Electric Field - Capacitance-Capacitance of Parallel Plate and Spherical Capacitors.

UNIT II

CONDUCTORS AND DIELECTRICS

Behavior of Conductors in an Electric Field-Conductors and Insulators – Electric Field Inside a Dielectric Material – Polarization – Dielectric Conductors and Dielectric Boundary Conditions – Energy Stored and Energy Density in a Static Electric Field – Current Density – Conduction and Convection – Current Densities – Ohm's Law in Point Form – Equation of Continuity.

UNIT III

MAGNETO STATICS

Static Magnetic Fields – Biot-Savart Law – Magnetic Field Intensity(MFI) due to a Straight Current Carrying Filament – MFI due to Circular, Square Filament – Solenoid Current Carrying Wire – Relation Between Magnetic Flux ,Magnetic Flux Density and MFI – Maxwell's Second Equation.

Ampere's Circuital Law and Its Applications Viz., MFI Due to an Infinite Sheet of Current and a Long Current Carrying Filament – Point Form of Ampere's Circuital Law – Maxwell's Third Equation.

Magnetic Force – Moving Charges in Magnetic Fields – Lorentz Force Equation – Force on Current Element in a Magnetic Field - Force on a Straight and Long Current Carrying Conductor in a Magnetic Field - Force Between two Straight and Parallel Current Carrying Conductor in a Magnetic Field – Magnetic Dipole and Dipole moment – A Differential Current Loop as a Magnetic Dipole – Torque on a Current Loop Placed in a Magnetic Field.

UNIT IV

MAGNETIC POTENTIAL

Scalar Magnetic Potential and Vector Magnetic Potential and its Properties - Vector Magnetic Potential due to Simple Configuration – Vector Poisson's Equations.

Self and Mutual Inductances – Neumann's Formulae – Determination of Self Inductance of a Solenoid and Toroid and Mutual Inductance Between a Straight, Long Wire and a Square Loop Wire in the Same Plane – Energy Stored and Intensity in a Magnetic Field.

UNIT V

TIME VARYING FIELDS

Time Varying Fields – Faraday's Law of Electromagnetic Induction – It's Integral and Point Forms – Maxwell's Fourth Equation. Statically and Dynamically Induced E.M.F's – Simple Problems – Modified Maxwell's Equations for Time Varying Fields – Displacement Current. Wave Equations – Uniform Plane Wave Motion in Free Space, Conductors and Dielectrics – Velocity, Wave Length, Intrinsic Impedence and Skin Depth – Poynting Theorem – Poynting Vector and its Significance.

Text Books:

- 1. Engineering Electromagnetics by William.H.Hayt, Mc.Graw Hill, 2010.
- 2. Electromagnetics by J.D.Kraus, Mc.Graw Hill Inc, 5th edition, 1999.
- 3. Field Theory Gangadhar, Khanna Publications, 2003.

- 1. Electrodynamics by Griffith, PHI, 3rd Edition, 1999.
- 2. Electromagnetic Fields by Sadiku Oxford University Press, 5th Edition, 2010.
- 3. Electromagnetics by Joseph Edminister, Tata Mc Graw Hill, 2006.



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(13A02402) CONTROL SYSTEMS ENGINEERING

Course Objective:

• In this course it is aimed to introduce to the students the principles and applications of control systems in everyday life. The basic concepts of block diagram reduction, time domain analysis solutions to time invariant systems and also deals with the different aspects of stability analysis of systems in frequency domain and time domain.

UNIT I

CONTROL SYSTEMS CONCEPTS

Open Loop and closed loop control systems and their differences- Examples of control systems-Classification of control systems, Feedback Characteristics, Effects of positive and negative feedback. Mathematical models – Differential equations of Translational and Rotational mechanical systems, and Electrical Systems, Block diagram reduction methods – Signal flow graph - Reduction using Mason's gain formula. Transfer Function of DC Servo motor - AC Servo motor - Synchro transmitter and Receiver UNIT II

TIME RESPONSE ANALYSIS

Step Response - Impulse Response - Time response of first order systems - Characteristic Equation of Feedback control systems, Transient response of second order systems - Time domain specifications - Steady state response - Steady state errors and error constants - Effects of proportional, integral, derivative Controllers, Design of P, PD, PI, PID Controllers.

UNIT III

STABILITY ANALYSIS IN FREQUENCY DOMAIN

The concept of stability – Routh's stability criterion – Stability and conditional stability – limitations of Routh's stability. The root locus concept - construction of root loci-effects of adding poles and zeros to G(s)H(s) on the root loci.

UNIT IV

FREQUENCY RESPONSE ANALYSIS

Introduction, Frequency domain specifications-Bode diagrams-Determination of Frequency domain specifications and transfer function from the Bode Diagram-Stability Analysis from Bode Plots. Polar Plots-Nyquist Plots- Phase margin and Gain margin-Stability Analysis.

Compensation techniques - Lag, Lead, Lead-Lag Compensators design in frequency Domain.

UNIT V

STATE SPACE ANALYSIS OF CONTINUOUS SYSTEMS

Concepts of state, state variables and state model, derivation of state models from Schematic models, differential equations, Transfer function, block diagrams, Diagonalization- Solving the Time invariant state Equations- State Transition Matrix and it's Properties. System response through State Space models.

Text Books:

- 1. Modern Control Engineering by Katsuhiko Ogata Prentice Hall of India Pvt. Ltd., 5th edition, 2010.
- 2. Control Systems Engineering by I. J. Nagrath and M. Gopal, New Age International (P) Limited, Publishers, 5th edition, 2007.

- 1. Control Systems Engineering by NISE 5th Edition John wiley & sons, 2010.
- 2. Control Systems by A. Nagoor Kani- First Edition RBA Publications, 2006.
- 3. Automatic Control Systems—by B. C. Kuo and Farid Golnaraghi John wiley and son's, 8th edition, 2003.

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(13A04407) ANALOG ELECTRONIC CIRCUITS

Course Objective:

• The aim of this course is to familiarize the student with the analysis and design of basic transistor amplifier circuits, Oscillators, Multi-vibrators and wave shaping.

Learning Outcome:

On completion of this course the student will be able to understand the

- *Methods of biasing transistors & Design of simple amplifier circuits.*
- *Mid band analysis of amplifier circuits using small signal equivalent circuits to determine gain, input impedance and output impedance.*
- Method of calculating cutoff frequencies and to determine bandwidth.
- Design and analyse different Oscillator circuits.
- Design of circuits for linear wave shaping and Multi-vibrators.

UNIT I Multistage Amplifiers

BJT and FET RC Coupled Amplifiers – Frequency Response. Cascaded Amplifiers. Calculation of Band Width of Single and Multistage Amplifiers. Concept of Gain Bandwidth Product.

UNIT II Feedback Amplifiers

Concept of Feedback Amplifiers – Effect of Negative feedback on the amplifier Characteristics. Four Feedback Amplifier Topologies. Method of Analysis of Voltage Series, Current Series, Voltage Shunt and Current Shunt feedback Amplifiers.

UNIT III Sinusoidal Oscillators

Condition for oscillations –LC Oscillators – Hartley, Colpitts, Clapp and Tuned Collector Oscillators – Frequency and amplitude Stability of Oscillators – Crystal Oscillators – RC Oscillators -- RC Phase Shift and Weinbridge Oscillators.

UNIT IV Large Signal Amplifiers

Class A power Amplifier, Maximum Value of Efficiency of Class A Amplifier, Transformer coupled amplifier – Push-Pull Amplifier – Complimentary Symmetry Circuits (Transformer Less Class B Power Amplifier) – Phase Inverters, Transistor Power Dissipation, Thermal Runaway, Heat Sinks.

UNIT V

Linear wave shaping: High pass, Low pass RC circuits-response for sinusoidal, Step, Pulse, Square and Ramp inputs, Clippers and Clampers

Multi-Vibrators: Analysis of Diode and transistor switching times, Analysis and Design of Bistable, Monosatable and Astable Multi-vibrators, Schmitt trigger Using Transistors.

Text Books:

- 1. Integrated Electronics Millman and Halkias
- 2. Pulse, Digital & Switching Waveforms by Jacob Milliman, Harbert Taub and Mothiki S Prakash Rao, 2nd edition 2008, Tata McGraw Hill Companies

- 1. K.Lal Kishore, "Electronic Circuit Analysis", Second Edition, BSP
- 2. Electronic Devices and Circuits, G.S.N. Raju, IK International Publications, New Delhi, 2006
- 3. Electronic Devices and Circuits Mottershead
- 4. A. Anand Kumar, "Pulse and Digital Circuits", PHI, 2005.
- 5. David A. Bell, "Solid State Pulse Circuits", 4th edition, 2002 PHI.

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(13A04303) SWITCHING THEORY AND LOGIC DESIGN

Course Objective:

• To provide fundamental concepts used in the design of digital systems and learn the methods for the design of digital circuits.

Learning Outcome:

- To introduce basic postulates of Boolean algebra and the methods for simplifying Boolean expressions
- To illustrate the concepts and study the procedures for the analysis and design of combinational circuits and sequential circuits
- To introduce the concepts of programmable logic devices.

UNIT I

NUMBER SYSTEM & BOOLEAN ALGEBRA

Digital systems, Binary Numbers, Number base conversions, Complements of numbers, Signed binary numbers, Binary codes. Boolean Algebra-Basic definition, Basic theorems and properties, Boolean Functions, Canonical & Standard forms, Other logic operations & Logic gates.

UNIT II

GATE LEVEL MINIMIZATION

The map method, four variable, K-map, Five variable map, POS & SOP Simplification, Don't care conditions, NAND & NOR Implementation, Other two level Implementation, Ex-or Function, Tabular Method-Simplification of Boolean function using tabulation Method.

UNIT III

ANALYSIS AND SYNTHESIS OF COMBINATIONAL CIRCUITS:

Combinational circuits, Analysis & Design procedure, Binary Adder-subtractor, Decimal Adder, Binary Multiplier, Magnitude comparator, Decoder, Encoders, Multiplexers.

UNIT IV

ANALYSIS AND SYNTHESIS OF SEQUNTIAL CIRCUITS:

Sequential Circuits, Latches Flips-Flops, Analysis of Clocked sequential circuits, State Reduction & Assignment, Design procedure, Registers & Counters – Registers, Shift Registers, Ripple Counters, Synchronous counters, other counters.

UNIT V

ASYNCHRONOUS SEQUENTIAL LOGIC & PROGRAMMABLE MEMORIES

Introduction, Analysis Procedure, Circuits with Latches, Design Procedure, Reduction of State flow tables, Race-free State Assignment, Hazards. Random Access Memory, Memory Decoding Error detection and correction, ROM,PLA, PAL.

Text Books:

- 1. M.Morris Mano & Michel D. Ciletti, "Digital Design", Pearson, 5th Edition.
- 2. Zvi KOhavi and Nirah K.Jha, "Switching theory and Finite Automata Theory", Cambridge, 3rd Edition

- 1. Subratha Goshal, "Digital Electronics", Cambridge.
- 2. Comer, "Digital & State Machine Design", Third Indian edition, OXFORD.

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(13A02403) ELECTRICAL POWER GENERATING SYSTEMS

Course Objective:

• Electrical Power plays significant role in day-to-day life of entire mankind. This course concerns the generation of conventional and non-conventional sources of energy along with the economic aspects.

UNIT I

THERMAL POWER GENERATING SYSTEMS

Block Diagram of Thermal Power Station (TPS) showing paths of Coal, Steam, Water, Air, Ash and Flue Gasses - Brief Description of TPS Components: Economizers, Boilers, Super Heaters, Turbines, Condensers, Chimney and Cooling Towers.

UNIT II

HYDRO & NUCLEAR POWER GENERATING SYSTEMS

Hydro Power: Selection of Site, Classification, Layout, Description of Main Components.

Nuclear Power: Nuclear Fission and Chain Reaction.- Nuclear Fuels.- Principle of Operation of Nuclear Reactor.-Reactor Components: Moderators, Control Rods, Reflectors and Coolants.- Radiation Hazards: Shielding and Safety Precautions.- Types of Nuclear Reactors and Brief Description of PWR, BWR and FBR.

UNIT III

SOLAR & WIND POWER GENERATING SYSTEMS

Solar Power Generation: Role and Potential of Solar Energy Options, Principles of Solar Radiation, Flat Plate and Concentrating Solar Energy Collectors, Different Methods of Energy Storage – PV Cell- V-I Characteristics.

Wind Power Generation: Role and potential of Wind Energy Option, Horizontal and Vertical Axis Wind Mills- Performance Characteristics- Power- Speed & Torque- Speed Characteristics-Pitch & Yaw Controls — Power Electronics Application — Economic Aspects.

UNIT IV

BIOGAS & GEOTHERMAL POWER GENERATING SYSTEMS

Biogas Power Generation: Principles of Bioconversion, Types of Biogas Digesters – Characteristics of Bio-Gas- Utilization- Economic and Environmental Aspects.

Geothermal and Ocean Power Generation: Principle of Geothermal Energy Methods of Harnessing-Principle of Ocean Energy-Tidal and Wave Energy-Mini Hydel Plants- Economic Aspects.

UNIT V

ECONOMIC ASPECTS OF POWER GENERATION

Load Curve, Load Duration and Integrated Load Duration Curves-Load Demand, Diversity, Capacity, Utilization and Plant Use Factors- Numerical Problems. Costs Of Generation and their Division Into Fixed, Semi-Fixed and Running Costs. Tariff Methods: Desirable Characteristics of a Tariff Method.-Flat Rate, Block-Rate, Two-Part, Three –Part, and Power Factor Tariff Methods and Numerical Problems.

Text Books:

- 1. A Text Book on Power System Engineering by M.L.Soni, P.V.Gupta, U.S.Bhatnagar and A.Chakraborti, Dhanpat Rai & Co. Pvt. Ltd., 1999.
- 2. Electric Power Generation Distribution and Utilization by C.L Wadhwa, New Age International (P) Ltd., 2005.
- 3. Non Conventional Energy Sources by G.D. Rai, Khanna Publishers, 2000.

- 1. Renewable Energy Resources John Twidell and Tony Weir, Second Edition, Taylor and Francis Group, 2006.
- 2. Electrical Power Generation, Transmission and Distribution by S.N.Singh., PHI, 2003.
- 3. Principles of Power Systems by V.K Mehta and Rohit Mehta S.CHAND& COMPANY LTD., New Delhi 2004.
- 4. Wind Electrical Systems by S. N. Bhadra, D. Kastha & S. Banerjee Oxford University Press, 2013.



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(13A02404) ELECTRICAL MACHINES – II

Course Objective:

• As an extension of Electrical machines I course this subject facilitates to study of the performance of Transformers and Induction motors which are the major part of industrial drives and agricultural pump sets.

UNIT I

SINGLE PHASE TRANSFORMERS

Single Phase Transformers- Constructional Details- Hystersis and Eddy Current Losses-Emf Equation - Operation on No Load and on Load - Phasor Diagrams

Equivalent Circuit - Losses and Efficiency-Regulation. All Day Efficiency - Effect of Variations of Frequency & Supply Voltage on Iron Losses.

UNIT II

PERFORMANCE OF SINGLE PHASE TRANSFORMERS

OC and SC Tests - Sumpner's Test - Predetermination of Efficiency and Regulation-Separation of Losses Test-Parallel Operation with Equal and Unequal Voltage Ratios - Auto Transformers-Equivalent Circuit - Comparison with Two Winding Transformers.

UNIT III

THREE PHASE TRANSFORMERS AND INDUCTION MOTORS

Three Phase Transformers - Connections - Y/Y, Y/ Δ , Δ /Y, Δ / Δ and Open Δ , Third Harmonics in Phase Voltages-Three Winding Transformers-Tertiary Windings- Scott Connection.

Polyphase Induction Motors-Construction Details of Cage and Wound Rotor Machines-Production of a Rotating Magnetic Field - Principle of Operation - Rotor Emf and Rotor Frequency - Rotor Reactance, Rotor Current and Pf at Standstill and During Operation.

UNIT IV

3-PHASE INDUCTION MOTOR CHARACTERISTICS

Rotor Power Input, Rotor Copper Loss and Mechanical Power Developed and Their Inter Relation-Torque Equation-Deduction From Torque Equation - Expressions for Maximum Torque and Starting Torque - Torque Slip Characteristic –Generator Operation - Double Cage and Deep Bar Rotors - Equivalent Circuit - Phasor Diagram - Crawling and Cogging -Circle Diagram-No Load and Blocked Rotor Tests-Predetermination of Performance

UNIT V

STARTING AND SPEED CONTROL OF INDUCTION MOTORS

Starting Methods and Starting Current and Torque Calculations, Speed Control-Change of Frequency; Pole Changing and Methods of Consequent Poles; Cascade Connection. Injection of an EMF.

Text Books:

- 1. Electrical Machinery & Transformers by Irving Kosow Pearson Publishers, Second Edition, 2012
- 2. Electric Machines -by I.J.Nagrath & D.P.Kothari, Tata Mc Graw Hill, 7th Edition., 2005

- 1. Performance and Design of AC Machines by MG.Say, BPB Publishers, 2002.
- 2. Theory of Alternating Current Machinery- by Langsdorf, Tata McGraw-Hill Companies, 2nd edition, 2008.
- 3. Electromechanics-II (transformers and induction motors) S. Kamakshaiah, Hitech publishers, 2005.
- 4. Electric Machinery A.E. Fitzgerald, C.Kingsley and S.Humans, Mcgraw Hill Companies, 6^{th} edition, 2003.



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(13A02405) ELECTRICAL MACHINES LAB - I

The following experiments are required to be conducted as compulsory experiments:

- 1. Magnetization Characteristics of DC Shunt Generator. Determination of Critical Field Resistance and Critical Speed.
- 2. Load Test on DC Shunt Generator. Determination of Characteristics.
- 3. Brake Test on DC Shunt Motor. Determination of Performance Curves.
- 4. Load Test on DC Compound Generator. Determination of Characteristics.
- 5. Hopkinson's Test on DC Shunt Machines. Predetermination of Efficiency.
- 6. Fields Test on DC Series Machines. Determination of Efficiency.
- 7. Swinburne's Test and Speed Control of DC Shunt Motor. Predetermination of Efficiencies.
- 8. Brake Test on DC Compound Motor. Determination of Performance Curves.

In addition to the above eight experiments, at least any two of the experiments from the following list are required to be conducted:

- 1. Load Test on DC Series Generator. Determination of Characteristics.
- 2. Retardation Test on DC Shunt Motor. Determination of Losses at Rated Speed.
- 3. Separation of Losses In DC Shunt Motor.



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(13A04305) ELECTRONIC DEVICES AND CIRCUITS LABORATORY

Course Objective:

• This Lab provides the students to get an electrical model for various semiconducter devices. Students can find and plot V_I characteristics of all semiconductor devices. Student learns the practical applications of the devices. They can learn and implement the concept of the feedback and frequency response of the small signal amplifier

Learning Outcome:

• Students able to learn electrical model for various semiconductor devices and learns the practical applications of the semiconductor devices

PART A: Electronic Workshop Practice

- 1. Identification, Specifications, Testing of R, L, C Components (Colour Codes), Potentiometers, Coils, Gang Condensers, Relays, Bread Boards.
- 2. Identification, Specifications and Testing of active devices, Diodes, BJTs, JFETs, LEDs, LCDs, SCR, UJT.
- 3. Soldering Practice- Simple circuits using active and passive components.
- 4. Study and operation of Ammeters, Voltmeters, Transformers, Analog and Digital Multimeter, Function Generator, Regulated Power Supply and CRO.

PART B: List of Experiments

(For Laboratory Examination-Minimum of Ten Experiments)

- 1. P-N Junction Diode Characteristics
 - Part A: Germanium Diode (Forward bias& Reverse bias)
 - Part B: Silicon Diode (Forward bias only)
- 2. Zener Diode Characteristics
 - Part A: V-I Characteristics
 - Part B: Zener Diode act as a Voltage Regulator
- 3. Rectifiers (without and with c-filter)
 - Part A: Half-wave Rectifier
 - Part B: Full-wave Rectifier
- 4. BJT Characteristics(CE Configuration)
 - Part A: Input Characteristics
 - Part B: Output Characteristics
- 5. FET Characteristics(CS Configuration)
 - Part A: Drain (Output) Characteristics
 - Part B: Transfer Characteristics
- 6. SCR Characteristics
- 7. UJT Characteristics
- 8. Transistor Biasing
- 9. CRO Operation and its Measurements
- 10. BJT-CE Amplifier
- 11. Emitter Follower-CC Amplifier
- 12. FET-CS Amplifier

PART C: Equipment required for Laboratory

- Regulated Power supplies 1.
- 2. Analog/Digital Storage Oscilloscopes
- Analog/Digital Function Generators 3.
- Digital Multimeters 4.
- Decade Résistance Boxes/Rheostats 5.
- Decade Capacitance Boxes 6.
- 7.
- Ammeters (Analog or Digital) Voltmeters (Analog or Digital) 8.
- Active & Passive Electronic Components 9.
- **Bread Boards** 10.
- 11.
- 12.

